# CSci 8980: Advanced Topics in Graphical Models Mixture Models, EM, Exponential Families

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#### Incremental EM

• Since  $z_i$  are independent, optimal  $\tilde{p}(Z) = \prod_i \tilde{p}(z_i)$ 

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- Then  $F(\tilde{p}, \theta) = \sum_{i} F_{i}(\tilde{p}_{i}, \theta)$  where

 $F_i(\tilde{p}_i, \theta) = E_{\tilde{p}_i}[\log p(x_i, z_i|\theta)] + H(\tilde{p}_i)$ 

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Incremental algorithm that works one point at a time

• Basic Incremental EM



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# Incremental EM (Contd.)

#### Basic Incremental EM

• E-step: Choose a data item *i* to be updated Set  $\tilde{p}_j^{(t)} = \tilde{p}_j^{(t-1)}$  for  $j \neq i$ Set  $\tilde{p}_i^{(t)} = p(z_i|x_i, \theta^{(t)})$ 

#### Basic Incremental EM

 E-step: Choose a data item *i* to be updated Set p̃<sub>j</sub><sup>(t)</sup> = p̃<sub>j</sub><sup>(t-1)</sup> for *j* ≠ *i* Set p̃<sub>i</sub><sup>(t)</sup> = p(z<sub>i</sub>|x<sub>i</sub>, θ<sup>(t)</sup>)
 M-step: Set θ<sup>(t)</sup> to argmax<sub>θ</sub> E<sub>p̃(t)</sub>[log p(x, z|θ)]

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#### Basic Incremental EM

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- M-step needs to look at all components of p̃
- Can be simplified by using sufficient statistics
- For a distribution  $p(x|\theta)$ , s(x) is a sufficient statistic if

 $p(x|s(x),\theta) = p(x|s(x)) \implies p(x|\theta) = h(x)q(s(x)|\theta)$ 

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### Incremental EM with Sufficient Statistics

EM with sufficient statistics

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, for  $j \neq i$   
Set  $\tilde{s}_{i}^{(t)} = E_{\tilde{p}_{i}}[s_{i}(x_{i}, z_{i})]$ , where  $\tilde{p}_{i}(z_{i}) = p(z_{i}|x_{i}, \theta^{(t-1)})$   
Set  $\tilde{s}^{(t)} = \tilde{s}^{(t-1)} - \tilde{s}_{i}^{(t-1)} + \tilde{s}_{i}^{(t)}$ 

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• Consider a mixture of 2 univariate Gaussians



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• Given  $s(x, z) = \sum_{i} s(x_i, z_i) = (n_1, n_2, m_1, m_2, q_1, q_2)$ 

$$\alpha = \frac{n_1}{n_1 + n_2} , \qquad \mu_h = \frac{m_h}{n_h} , \qquad \sigma_h^2 = \frac{q_h}{n_h} - \left(\frac{m_h}{n_h}\right)^2$$

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#### Sparse EM

• Consider a mixture model with many components

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- Consider a mixture model with many components
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- $S_t = \text{set of plausible values}$ 
  - Can be determined by a reasonable hueristic

Generalized EM



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#### Other Variants

#### Generalized EM

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- Hard clustering, equivalent to kmeans
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- But optimizes a lower bound on  $L(\theta)$
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- EM updates are a special case of the general technique

• For multi-variate Gaussians, each component

$$p_h(x|\mu_h, \Sigma_h) = rac{1}{(2\pi)^{d/2}|\Sigma_h|^{1/2}} \exp\left(-rac{1}{2}(x-\mu_h)^T \Sigma_h^{-1}(x-\mu_h)
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• The Mixture of Gaussians (MoG) model

$$p(x|\alpha,\Theta) = \sum_{h=1}^{k} \alpha_h p_h(x|\mu_h, \Sigma_h)$$

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- One of the most widely used mixture models
- Recent years have seen progress on non-EM algorithm

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# EM for Mixture of Gaussians: E-step

• E-step is a direct application of Bayes rule

$$\rho(h|x,\alpha,\Theta) = \frac{\alpha_h p_h(x|\mu_h, \Sigma_h)}{\sum_{h'=1}^k \alpha_{h'} p_{h'}(x|\mu_{h'}, \Sigma_{h'})}$$

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- Use current parameter values on the r.h.s.
- Incremental and sparse variants can be applied in practice

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# EM for Mixture of Gaussians: M-step

• The auxiliary function

$$Q(\theta, \theta^{(t-1)}) = \sum_{i} \sum_{h} \log(\alpha_{h}) p(h|x_{i}|\theta^{(t-1)}) + \sum_{i} \sum_{h} \log p_{h}(x|\mu_{h}, \Sigma_{h}) p(h|x_{i}, \theta^{(t-1)})$$

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• Optimize over  $(\alpha_h, \mu_h, \Sigma_h), [h]_1^k$ 

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- Optimize over  $(\alpha_h, \mu_h, \Sigma_h), [h]_1^k$
- *α* is a discrete distribution, forms additional constraint
- Focus on first term for  $\alpha_h$ , true for all mixtures

# EM for Mixture of Gaussians: M-step

The auxiliary function

$$Q(\theta, \theta^{(t-1)}) = \sum_{i} \sum_{h} \log(\alpha_{h}) p(h|x_{i}|\theta^{(t-1)}) + \sum_{i} \sum_{h} \log p_{h}(x|\mu_{h}, \Sigma_{h}) p(h|x_{i}, \theta^{(t-1)})$$

- Optimize over  $(\alpha_h, \mu_h, \Sigma_h), [h]_1^k$
- *α* is a discrete distribution, forms additional constraint
- Focus on first term for  $\alpha_h$ , true for all mixtures
- Focus on second term for  $(\mu_h, \Sigma_h)$

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### EM for Mixture of Gaussians: M-step (Contd.)

• For any finite mixture model

$$\alpha_h = \frac{1}{N} \sum_{i=1}^{N} p(h|x_i, \theta^{(t-1)})$$

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For Mixture of Gaussians

$$\mu_h = \frac{\sum_i x_i p(h|x_i, \theta^{(t-1)})}{\sum_i p(h|x_i, \theta^{(t-1)})}$$
  
$$\Sigma_h = \frac{\sum_i p(h|x_i, \theta_n)(x_i - \mu_h)(x_i - \mu_h)^T}{\sum_i p(h|x_i, \theta_n)}$$

# Exponential Family Distributions

Multi-variate parametric distributions of the form

 $p_{\psi}(x|\theta) = \exp(x^{T}\theta - \psi(\theta))p_{0}(x)$ 

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Examples: Gaussian, Bernoulli, Poisson, Multinomial, Dirichlet

• The Laplace transform viewpoint

$$L(\theta) = \exp(\psi(\theta)) = \int_{x} \exp(\mathbf{x}^{T}\theta) p_{0}(x) \, dx = E_{p_{0}}[\exp(\mathbf{x}^{T}\theta)]$$

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Hence

$$\begin{split} \lambda \psi(\theta_1) + (1-\lambda)\psi(\theta_2) \\ &= \log\left(E_{p_0}[\exp(x^{\mathsf{T}}\theta_1)]^{\lambda}E_{p_0}[\exp(x^{\mathsf{T}}\theta_2)]^{1-\lambda}\right) \\ &\geq \log\left(E_{p_0}[\exp(x^{\mathsf{T}}(\lambda\theta_1 + (1-\lambda)\theta_2))]\right) \\ &= \psi(\lambda\theta_1 + (1-\lambda)\theta_2) \end{split}$$

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• The cumulant  $\psi(\theta)$  is a convex function

# Maximum Likelihood Estimation, Conjugate

• Let s = s(x) be the sufficient statistic for a set of points x

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- Technically,  $\psi, \phi$  are "Legendre" functions

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# Mixtures of Exponential Family Distributions

• A finite mixture model

$$p(x|\alpha,\Theta) = \sum_{h=1}^{k} \alpha_h p_{\psi}(x|\theta_h)$$

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- All mixture components are of the same family
- $\theta$  determines the distribution in the family

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## Mixtures of Exponential Family Distributions

A finite mixture model

$$p(x|\alpha,\Theta) = \sum_{h=1}^{k} \alpha_h p_{\psi}(x|\theta_h)$$

- $\psi$  determines the family
- All mixture components are of the same family
- $\theta$  determines the distribution in the family
- Each component has different parameters

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# Mixtures of Exponential Family Distributions (Contd.)

• E-step: Exactly same as before

$$\alpha_h = \frac{1}{N} \sum_{i=1}^{N} p(h|x_i, \theta^{(t-1)})$$

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### Mixtures of Exponential Family Distributions (Contd.)

• E-step: Exactly same as before

$$\alpha_h = \frac{1}{N} \sum_{i=1}^{N} p(h|x_i, \theta^{(t-1)})$$

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•  $\nabla\psi$  is monotonic increasing, inverse is well defined

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- $\nabla\psi$  is monotonic increasing, inverse is well defined
- Recall the expression for  $\mu_h$  for Gaussian mixtures

# Mixture Models as a Bayes Net



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