

VAE 4: Challenging Assumptions behind Disentanglement

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Disentanglement is impossible without inductive bias

Experimental results



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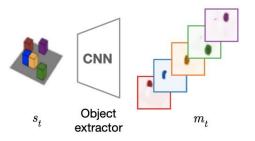
No formal definition, briefly, separating the distinct, informative factors of variations in the data

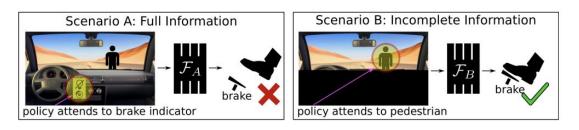
Entanglement: a random variable X = [a+b, a-b, a+2b, b]

Disentanglement: Z = [a,b]

Why is it useful?

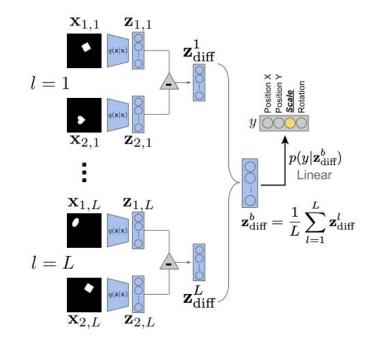
- Customized generation
- Causality: $p(x)\underline{p(y|x)}, p(y)p(x|y)$
- Robot tasks





β-VAE





 $\mathcal{F}(\theta, \phi, \beta; \mathbf{x}, \mathbf{z}) \geq \mathcal{L}(\theta, \phi; \mathbf{x}, \mathbf{z}, \beta) = \mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x})}[\log p_{\theta}(\mathbf{x}|\mathbf{z})] - \beta D_{KL}(q_{\phi}(\mathbf{z}|\mathbf{x})||p(\mathbf{z}))$



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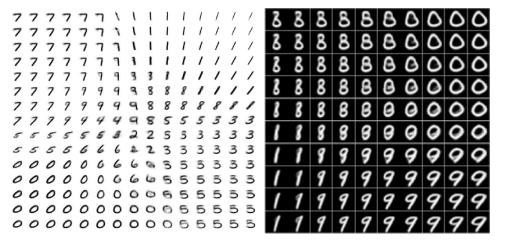
Experimental results

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For any disentanglement representation, we can find infinite many equivalent representations. It's impossible to get the disentanglement representation without inductive bias.

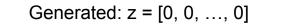
Prior knowledge

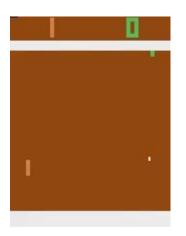
Theorem 1. For d > 1, let $\mathbf{z} \sim P$ denote any distribution which admits a density $p(\mathbf{z}) = \prod_{i=1}^{d} p(\mathbf{z}_i)$. Then, there exists an infinite family of bijective functions $f : \operatorname{supp}(\mathbf{z}) \rightarrow$ $\operatorname{supp}(\mathbf{z})$ such that $\frac{\partial f_i(\mathbf{u})}{\partial u_j} \neq 0$ almost everywhere for all *i* and *j* (i.e., \mathbf{z} and $f(\mathbf{z})$ are completely entangled) and $P(\mathbf{z} \leq \mathbf{u}) = P(f(\mathbf{z}) \leq \mathbf{u})$ for all $\mathbf{u} \in \operatorname{supp}(\mathbf{z})$ (i.e., they have the same marginal distribution).

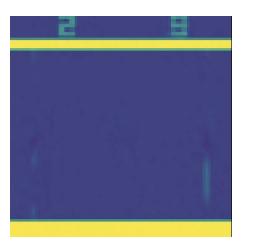




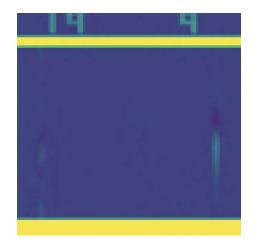
Data







Generated: z = [0, 0, 0, 1, ..., 0]





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Methods:

- β-VAE
- AnnealedVAE
- FactorVAE
- β-TCVAE
- DIP-VAE-I
- DIP-VAE-II

Metrics:

- β-VAE score
- FactorVAE score
- Mutual Information Gap (MIG)
- DCI Disentanglement
- Modularity
- SAP score

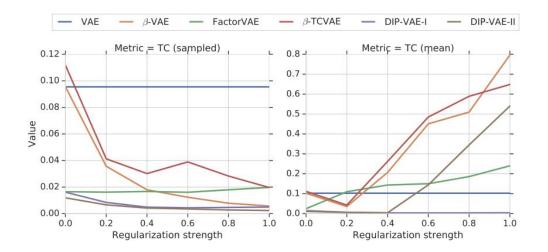
Datasets

- dSprites
- Cars3D
- SmallNORB
- Shapes3D
- Color-dSprites
- Noisy-dSprites
- Scream-dSprites



Common practice in latent representation:

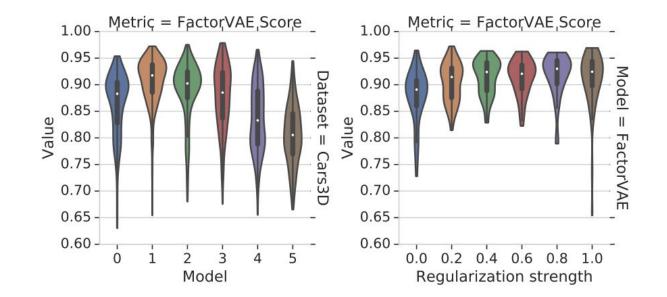
- Training: $z \sim N(\mu(z), \sigma(z))$
- Testig: $\mu(z)$





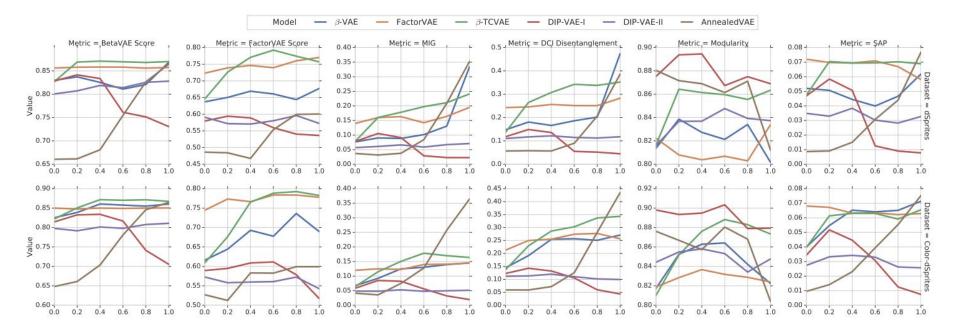
	Dataset = Noisy-dSprites										
BetaVAE Score (A) -	100	80	44	41	46	37	-				
FactorVAE Score (B) -	80	100	49	52	25	38	-				
MIG (C) -	44	49	100	76	6	42	-				
Disentanglement (D) -	41	52	76	100	-8	38	-				
Modularity (E) -	46	25	6	-8	100	13	-				
SAP (F) -	37	38	42	38	13	100	-				
	(Å)	(B)	(C)	(D)	(E)	(F)					



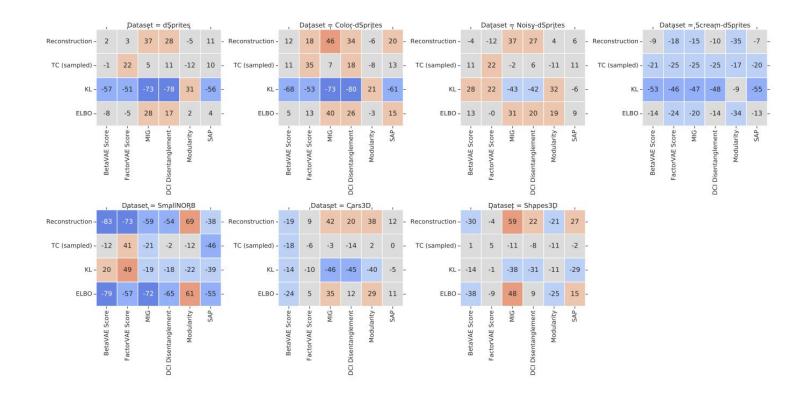




- 1. Strategy should not depend on the score, which needs labels and the full generative model
- 2. No hyperparameters and models work the best every time



Unsupervised loss vs. disentanglement scores



The same dataset and metric: 80.7%

Different datasets and the same metric: 59.3%

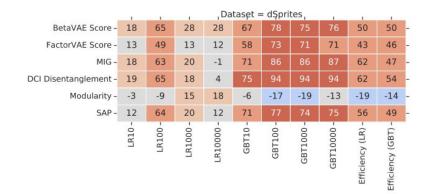
Different datasets and metrics: 54.9%

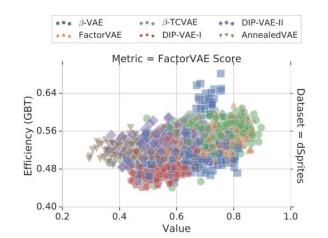
, Metric = PCI Disentanglement											
dSprites (I) -	100	95	65	65	34	64	46 -				
Color-dSprites (II) -	95	100	61	60	21	63	47 -				
Noisy-dSprites (III) -	65	61	100	68	17	64	59 -				
Scream-dSprites (IV) -	65	60	68	100	36	93	69 -				
SmallNORB (V) -	34	21	17	36	100	21	-9 -				
Cars3D (VI) -	64	63	64	93	21	100	85 -				
Shapes3D (VII) –	46	47	59	69	-9	85	100 -				
	(1)	(II)	()	(IV)	(V)	(VI)	VII				

Ι

Basically, better disentanglement score leads to better performance in downstream tasks

But no clear evidence it leads to better sample complexity







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Make inductive bias explicit, figure out how to select the hyperparameters without labels

Concrete the benefits of the disentanglement

Evaluate disentanglement methods over diverse datasets

- 2017 (ICLR): I. Higgins, L. Matthey, A. Pal, C. Burgess, X. Glorot, M. Botvinick, S. Mohamed, A. Lerchner. <u>beta-VAE: Learning basic visual concepts with a constrained variational framework</u>. ICLR, 2017.
- 2019 (ICML): F. Locatello, S. Bauer, M. Lucic, G. Rätsch, S. Gelly, B. Scholkopf, O. Bachem. <u>Challenging</u> common assumptions in the unsupervised learning of disentangled representations. ICML, 2019.
- 2020 (ICLR): T. Kipf, E. Pol, M. Welling. <u>Contrastive Learning of Structured World Models</u>. ICLR, 2020.
- 2019 (NeurIPS): P. Haan, D. Jayaraman, S. Levine. <u>Causal Confusion in Imitation Learning</u>. NeurIPS, 2019.