Robust 1-bit Compressed Sensing and Sparse Logistic Regression: A Convex Programming Approach

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At least *m* cuts s.t. the image is clear?



Outline

- What's compressed sensing
- What's 1-bit compressed sensing
- Mean width $[w \leftrightarrow (n, s)] [m \leftrightarrow w]$
- 1-bit compressed sensing
- Theorem 1.1











At least *m* bits s.t. the image is clear?

What's 1-bit compressed sensing

- Dramatic compression
 - $-n \rightarrow m$ (compressed sensing)
 - m bits (1-bit)
- Could we recover signal accurately?



P. T. Boufounos and R. G. Baraniuk. <u>1-bit Compressive Sensing</u>, in Proceedings of Conference on Information Science and Systems (CISS), Princeton, NJ, March 2008.

What's 1-bit compressed sensing

Model CS $Y_{(m,1)} = A_{(m,n)} x_{(n,1)}$ $v_{i} = \langle a_{i}, x \rangle, \quad i = 1,...m$ 1-bit CS $y_i = \theta(\langle a_i, x \rangle), \quad i = 1, \dots, m, y_i = \{+1, -1\}$ $-1 \le \theta(z) \le 1, \quad \theta(z) : \text{Sign, logistic}, \dots$ $y_i = \theta(\langle a_i, x \rangle + v_i), \quad i = 1, \dots, m, v_i : \text{noise}$ $\max \sum_{i=1}^{n} y_i < a_i, x'>, \text{ subject to } x' \in K$ convex program (Convex) m=?

This paper

• If 1-bit measurement is *noisy*,

 $-m = O(s \log(n/s)) \quad \text{to recover the signal } X$ $-Accuracy \quad m \ge C\delta^{-2}w(K)^2 \qquad \delta \downarrow \Rightarrow m \uparrow$ $-Probability > 1 - 8\exp(-c\delta^2 m) \qquad m \uparrow \Rightarrow P \uparrow$



11

This paper— 3 surprising conclusions $y_i = \theta(\langle a_i, x \rangle + v_i), \quad v_i \sim N(0, \sigma^2)$

- 1. The signal x can be estimated even if each measurement is flopped with probability nearly $\frac{1}{2}$.
- 2. The signal *x* can be estimated even when the noise level σ eclipses the magnitude of the linear measurements. $\langle a_i, x \rangle$
- 3. If the noise is big enough, nothing is lost by quantizing to 1-bit (minimax error).

This paper

$$y_i = \theta(\langle a_i, x \rangle)$$
$$E\theta(g)g =: \lambda > 0$$

 λ : correlation coefficient

: a_i are standard Gaussian random vectors & $\|x\|_2 = 1$ g : standard Gaussian random vector $Ey_i < a_i, x \ge E\theta(g)g = \lambda$ $\theta \uparrow (< a_i, x >)$



Mean width

η

T

• How to measure the size of K?

$$\sup_{u \in K} \langle \eta, u \rangle - \inf_{v \in K} \langle \eta, v \rangle = \sup_{x \in K - K} \langle \eta, x \rangle$$
$$\widetilde{\mathcal{L}}(K) = \sum_{v \in K} \langle \eta, v \rangle = \sum_{x \in K - K} \langle \eta, x \rangle$$

$$\widetilde{w}(K) \coloneqq E \sup_{x \in K-K} \langle \eta, x \rangle$$

$$w(K) \coloneqq E \sup_{x \in K-K} \langle g, x \rangle, \quad g \sim N(0, I)$$

- g : standard Gaussian random vector
- Proposition 2.1 (mean width)
 2) w(K) = w(conv(K))





• Theorem 5.2 (Gaussian Concentration inequality) $P(x - E[x] \ge t) \le \exp\left(-\frac{t^2}{2}\right), \text{ where } t > 0$







Mean width

$$P(\max_{|T|=s} \|g_T\|_2 \ge \sqrt{s} + t) \le {n \choose s} \exp\left(-\frac{t^2}{2}\right)$$

$$\because {n \choose s} \le \exp(s \log(en/s))$$

$$\begin{split} &P(\max_{|T|=s} \left\|g_{T}\right\|_{2} \geq \sqrt{s} + t) \leq \exp(s\log(en/s))\exp(-\frac{t^{2}}{2}) \\ &P(\max_{|T|=s} \left\|g_{T}\right\|_{2} \geq \sqrt{s} + t) \leq \exp(s\log e + s\log(n/s) - \frac{t^{2}}{2}) \\ &P(\max_{|T|=s} \left\|g_{T}\right\|_{2} \leq \sqrt{s} + t) \geq 1 - \exp(s\log e + s\log(n/s) - \frac{t^{2}}{2}) \end{split}$$

f(n,s)? High probability?



Theorem 1.1 (Fixed Signal Estimation, Random Noise): Let a_1, \ldots, a_m be independent standard Gaussian random vectors in \mathbb{R}^n , and let K be a subset of the unit Euclidean ball in \mathbb{R}^n . Fix $x \in K$ satisfying $||x||_2 = 1$. Assume that the measurements y_1, \ldots, y_n follow the model above.⁴ Then for each $\beta > 0$, with probability at least $1 - 4 \exp(-2\beta^2)$ the solution \hat{x} to the optimization problem (I.7) satisfies
Robust recovery 8

Robust recovery $\|\hat{\boldsymbol{x}} - \boldsymbol{x}\|_{2}^{2} \leq \frac{8}{\lambda\sqrt{m}}(w(K) + \beta).$

 $m = O\Big(w(K)^2\Big)$

 $\underline{m \ge C\delta^{-2}w(K)^{2}, P > 1 - 8\exp(-c\delta^{2}m) \text{ satisfies } \left\|\hat{x} - x\right\|_{2}^{2} \le \delta / \lambda}$ $\delta: \text{Accuracy(defined by users)}$

Mean width



w(K) = w(conv(K))

Mean width $W(K) = W(S_{n,s})$

If $x \in S_{n,s}$, $||x||_1 \le \sqrt{s}$ (: Cauchy-Schwarz inequality) $K_{n,s} = \left\{ x \in \mathbb{R}^n : \|x\|_{2} \le 1, \|x\|_{1} \le \sqrt{s} \right\} = B_2^n \cap \sqrt{s} B_1^n$ $conv(S_{n,s}) \subset K_{n,s} \subset 2conv(S_{n,s})$ ("Lemma 3.1 [23]) $w(K_{n,s}) \le 2w(conv(S_{n,s})) \le C\sqrt{s\log(2n/s)}$ $\Rightarrow w(K_{n,s}) \le C\sqrt{s\log(2n/s)}$ $\max \sum y_i < a_i, x'>$, subject to $||x'||_2 \le 1$ and $||x'||_1 \le \sqrt{s}$

Mean width



$$m \ge C\delta^{-2}s\log(2n/s)$$
$$\Rightarrow m = O(s\log(n/s))$$

1-bit compressed sensing

1. The signal x can be estimated even if each measurement is flopped with probability nearly ¹/₂. $y_i = \xi_i sign(\langle a_i, x \rangle)$ $P\{\xi_i = 1\} = p$ $E[\xi_1] = 1 \bullet p \bullet sign(z) + (-1) \bullet (1-p) \bullet sign(z)$ = 2(p-1/2)sign(z) $\lambda = 2(p - 1/2)E|g|$ $m \ge C\delta^{-2}(p-1/2)^{-2}s\log(2n/s)$

1-bit compressed sensing

2. The signal x can be estimated even when the noise level σ eclipses the magnitude of the linear measurements $E|\langle a_i, x \rangle| = \sqrt{2/\pi}$

$$y_{i} = \theta(\langle a_{i}, x \rangle + v_{i}), v_{i} \sim N(0, \sigma^{2})$$
$$\lambda = \sqrt{\frac{2}{\pi\sigma^{2}}} \exp(-g^{2}/2\sigma^{2}) = \sqrt{\frac{2}{\pi(\sigma^{2}+1)}}$$
$$m \geq C\delta^{-2}(\sigma^{2}+1)s \log(2n/s)$$
$$\| \hat{\rho} = \|^{2} \leq C \sqrt{(\sigma^{2}+1)s \log(2n/s)}$$

m

 $||x - x||_2 \le C_{\sqrt{-1}}$

1-bit compressed sensing

3. If the noise is big enough, nothing is lost by quantizing to 1-bit (minimax error)

$$y_i = \langle a_i, x \rangle + v_i$$
 $y_i = \theta(\langle a_i, x \rangle + v_i), v_i \sim N(0, \sigma^2)$

minimax error [24]

$$\delta = c \sigma_{\sqrt{\frac{s \log(2n/s)}{m}}} \qquad \|\hat{x} - x\|_{2}^{2} \le C_{\sqrt{\frac{(\sigma^{2} + 1)s \log(2n/s)}{m}}}$$

Up to a constant
 σ>1

Theorem 1.1 (Fixed Signal Estimation, Random Noise): Let a_1, \ldots, a_m be independent standard Gaussian random vectors in \mathbb{R}^n , and let K be a subset of the unit Euclidean ball in \mathbb{R}^n . Fix $x \in K$ satisfying $||x||_2 = 1$. Assume that the measurements y_1, \ldots, y_n follow the model above.⁴ Then for each $\beta > 0$, with probability at least $1 - 4 \exp(-2\beta^2)$ the solution \hat{x} to the optimization problem (I.7) satisfies $\frac{\operatorname{Robust recovery}}{||\hat{x} - x||_2^2} \leq \frac{8}{\lambda \sqrt{m}} (w(K) + \beta).$

$$f_{x}(x') = \frac{1}{m} \sum_{i=1}^{m} y_{i} \langle a_{i}, x' \rangle$$

$$f_{x}(\hat{x}) \geq f_{x}(x), x \text{ is feasible set}$$

$$\hat{x}: \text{ solution of max} \sum_{i=1}^{m} y_{i} < a_{i}, x' >, \text{ subject to } x' \in K$$

$$Lemma \ 4.1 \ (Expectation): \text{ Fix } \mathbf{x}' \in \mathbb{R}^{n}. \text{ Then}$$

$$\mathbb{E}f_{\pmb{x}}(\pmb{x}') = \lambda \langle \pmb{x}, \pmb{x}' \rangle$$

and thus

$$\mathbb{E}[f_{\boldsymbol{x}}(\boldsymbol{x}) - f_{\boldsymbol{x}}(\boldsymbol{x}')] = \lambda(1 - \langle \boldsymbol{x}, \boldsymbol{x}' \rangle) \geq \frac{\lambda}{2} \|\boldsymbol{x} - \boldsymbol{x}'\|_2^2.$$

$$\begin{split} & Proposition \ 4.2 \ (Concentration): \ \text{For each } t > 0, \ \text{we have} \\ & \left\{ \mathbb{P} \left\{ \sup_{\boldsymbol{z} \in K-K} |f_{\boldsymbol{x}}(\boldsymbol{z}) - \mathbb{E} f_{\boldsymbol{x}}(\boldsymbol{z})| \ge 4w(K)/\sqrt{m} + t \right\} \right\} \\ & \leq 4 \exp(-mt^2/8). \\ & 0 \leq f_x(\hat{x}) - f_x(x) = f_x(\hat{x} - x) \leq E \Big[f_x(\hat{x} - x) \Big] + \frac{4w(K)}{\sqrt{m}} + t \\ & \because P(\sup_{z \in K-K} \left| f_x(z) - E f_x(z) \right| \le \frac{4w(K)}{\sqrt{m}} + t) \ge 1 - 4 \exp(-mt^2/8) \\ & f_x(z) - E f_x(z) \le \frac{4w(K)}{\sqrt{m}} + t \Longrightarrow f_x(z) \le E f_x(z) + \frac{4w(K)}{\sqrt{m}} + t \\ & f_x(\hat{x} - x) \le E f_x(\hat{x} - x) + \frac{4w(K)}{\sqrt{m}} + t \end{split}$$

30

Lemma 4.1 (Expectation): Fix $\mathbf{x}' \in \mathbb{R}^n$. Then

$$\mathbb{E} f_{\pmb{x}}(\pmb{x}') = \lambda \langle \pmb{x}, \pmb{x}' \rangle$$

and thus

$$\mathbb{E}[f_{\boldsymbol{x}}(\boldsymbol{x}) - f_{\boldsymbol{x}}(\boldsymbol{x}')] = \lambda(1 - \langle \boldsymbol{x}, \boldsymbol{x}' \rangle) \geq \frac{\lambda}{2} \|\boldsymbol{x} - \boldsymbol{x}'\|_{2}^{2}.$$

31

$$f_x(\hat{x} - x) \le E[f_x(\hat{x} - x)] + \frac{4w(K)}{\sqrt{m}} + t$$

$$\leq -\frac{\lambda}{2} \|\hat{x} - x\|_{2}^{2} + \frac{4w(K)}{\sqrt{m}} + t$$
 (:: Lemma 4.1)

choose $t = 4\beta / \sqrt{m}$

$$\|\hat{x} - x\|_{2}^{2} \le \frac{8}{\lambda\sqrt{m}}(w(K) + \beta)$$
, P > 1 - 4exp(-2 β)

Proposition 4.2

Lemma 5.1 (Symmetrization): Let $\varepsilon_1, \varepsilon_2, \ldots, \varepsilon_m$ be independent Rademacher random variables.⁸ Then

$$\mu := \mathbb{E} \sup_{\boldsymbol{z} \in K-K} \left| f_{\boldsymbol{x}}(\boldsymbol{z}) - \mathbb{E} f_{\boldsymbol{x}}(\boldsymbol{z}) \right|$$

$$\leq 2\mathbb{E} \sup_{\boldsymbol{z} \in K-K} \frac{1}{m} \left| \sum_{i=1}^{m} \varepsilon_{i} y_{i} \langle \boldsymbol{a}_{i}, \boldsymbol{z} \rangle \right|.$$
(V.1)

Furthermore, we have the deviation inequality

$$\mathbb{P}\left\{\sup_{\boldsymbol{z}\in K-K} |f(\boldsymbol{z}) - \mathbb{E}f(\boldsymbol{z})| \ge 2\mu + t\right\}$$

$$\le 4\left\{\sup_{\boldsymbol{z}\in K-K} \left|\sum_{i=1}^{m} \varepsilon_{i} y_{i} \langle \boldsymbol{a}_{i}, \boldsymbol{z} \rangle\right| > t/2\right\}.$$
(V.2)

[19] M. Ledoux and M. Talagrand, *Probability in Banach Spaces: Isoperimetry and Processes. Berlin, Germany: Springer-Verlag,* 1991. [chapter 6.1]

$$\begin{aligned} & \operatorname{Proposition} 4.2 \\ & \sup_{z \in K - K} \frac{1}{m} \left| \sum_{i=1}^{m} \varepsilon_{i} y_{i} \langle a_{i}, z \rangle \right|^{dist} = \sup_{z \in K - K} \frac{1}{m} \left| \sum_{i=1}^{m} \langle a_{i}, z \rangle \right|^{dist} = \frac{1}{\sqrt{m}} \sup_{z \in K - K} \left| \langle g, z \rangle \right| \\ &= \frac{1}{\sqrt{m}} \sup_{z \in K - K} \left| g, z \rangle \qquad (V.4) \\ & E \sup_{z \in K - K} \left| f_{x}(z) - Ef_{x}(z) \right| \le \frac{2}{\sqrt{m}} E \sup_{z \in K - K} \left\langle g, z \right\rangle = \frac{2w(K)}{\sqrt{m}} \quad (V.5) \\ & P \left\{ \sup_{z \in K - K} \left| f_{x}(z) - Ef_{x}(z) \right| \ge \frac{4w(K)}{\sqrt{m}} + t \right\} \le 4P \left\{ \frac{1}{\sqrt{m}} \sup_{z \in K - K} \left\langle g, z \right\rangle > \frac{t}{2} \right\} \\ & \because P \left\{ \sup_{z \in K - K} \left| g, z \right\rangle \ge w(K) + r \right\} \le \exp(-\frac{r^{2}}{2}), \text{choose } r = t\sqrt{m}/2 \\ & P \left\{ \sup_{z \in K - K} \left| f_{x}(z) - Ef_{x}(z) \right| \ge \frac{4w(K)}{\sqrt{m}} + t \right\} \le 4\exp(-t^{2}m/8) \end{aligned}$$

Conclusions

- If 1-bit measurement is *noisy*,
 - $m = O(s \log(n/s))$ to recover the signal X - Accuracy: $m \ge C\delta^{-2}w(K)^2$ - Probability >1-8exp(- $c\delta^2 m$)



Reference

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- 3. Richard G. Baraniuk, "**Compressive Sensing**," IEEE Signal Processing Magazine, 2007.
- Qaisar S., Bilal R.M., Wafa Iqbal, Naureen M. and Lee S., "Compressive Sensing: From Theory to Applications A Survey," Journal of Communications and Networks, 2013.